

# UGP40

Unità gripper UNIVERSAL per assemblaggio



U	G	P	4	0	V	B	E	
1	2	3	4	5	6	7		

## 1 Serie

**UG** = Unità gripper **UNIVERSAL** per assemblaggio, con regolazione continua angolo d'apertura da: **0° a 95° max**  
L'angolo di apertura può variare a seconda della posizione e della tipologia del pressore

## 2 Versione

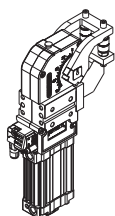
**P** = Pneumatica standard

## 3 Taglia

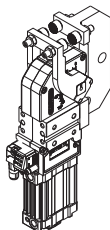
**40** = Ø 40 mm

## 4 Posizione pressore

**V** = 90°



**O** = 180°



## 5 Tipo di movimento

**B** = Doppio movimento; doppia serie di dita. Solo per unità con pressore in posizione verticale

**F** = Doppio movimento; singola serie di dita. Solo per unità con pressore in posizione verticale

**L** = Singolo movimento; doppia serie di dita

**H** = Doppio movimento; senza dita di presa. Solo per unità con pressore in posizione verticale

## 6 Sensore di posizione

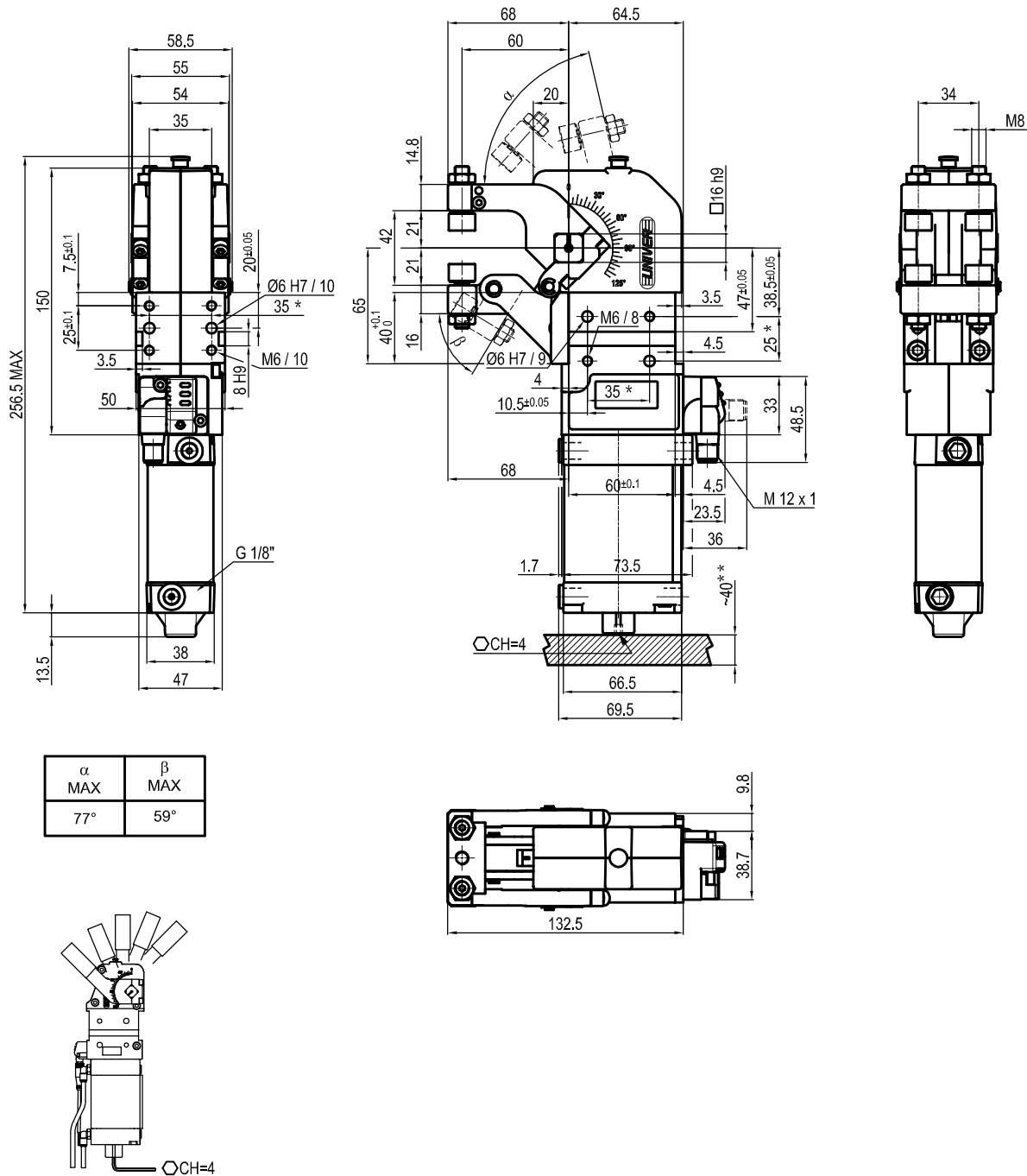
**N** = Senza sensore (con piastra di chiusura)

**E** = Sensore elettronico con connettore M12 orientabile

## 7 Materiale pressore

**S** = Pressore in acciaio (senza indicazioni, il pressore verrà fornito in alluminio)

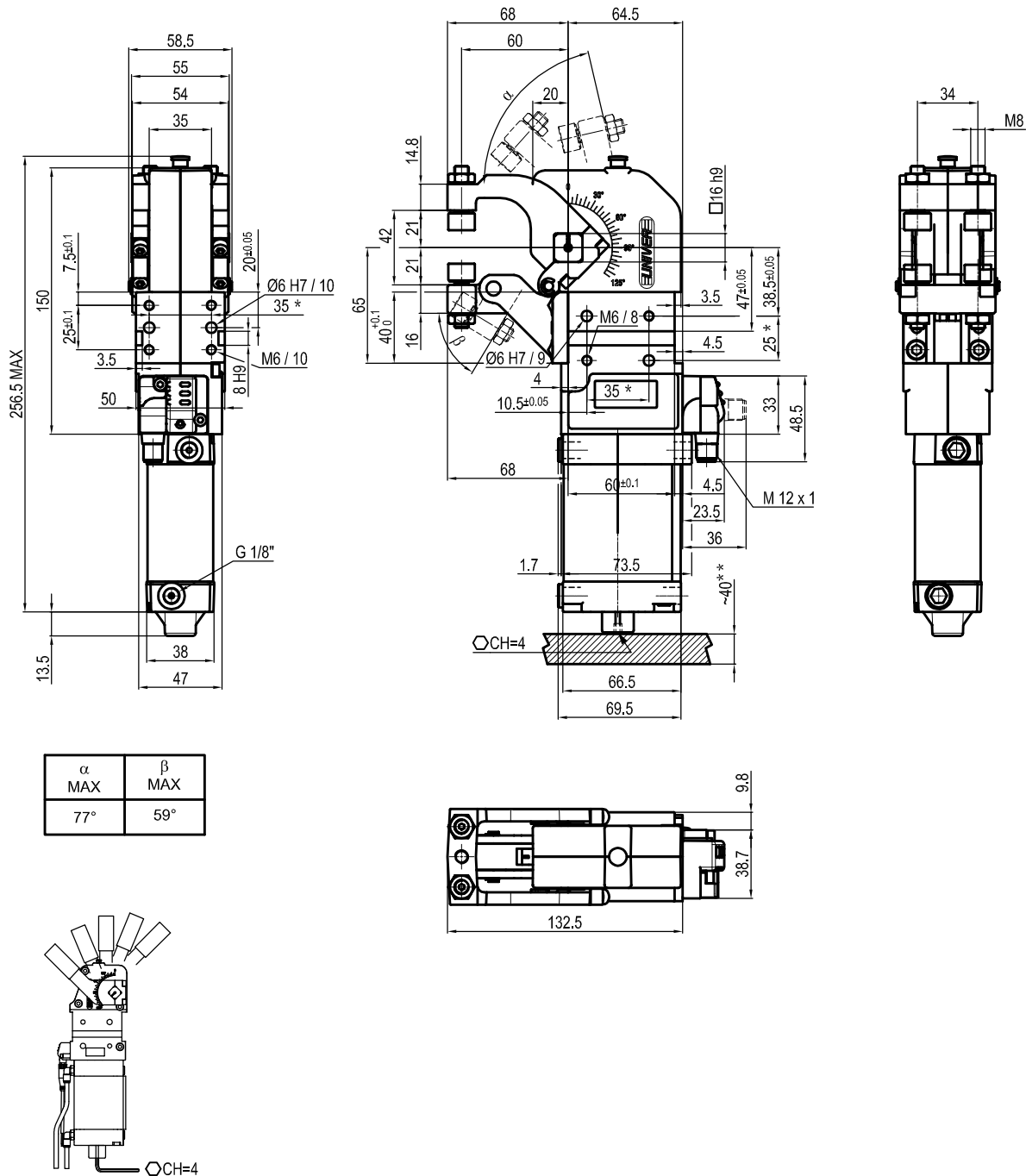




Bore Ø	Holding moment	Clamping moment	Weight (Clamping arm not included)
40 mm	600 Nm	170 Nm	1.5 Kg

Min./max. operating pressure: 0,4 / 0,6 MPa  
 Operating temperature: 5° + 45° C  
 Opening angle: **adjustable from 0° to 77°**  
 Vertical arm mount position  
 Electronic sensor with M12 swivel connector that can be orientated at 0° or 90°  
 Supply voltage: 10+30 Vdc  
 IP code: **IP 65**  
 Pneumatic ports on both sides

\* : TOLERANCE BETWEEN DOWEL HOLES ± 0.02, TO SCREW HOLES ± 0.1  
 \*\* : AREA TO ACCESS ANGLE ADJUSTMENT



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Vertical arm mount position

With steel arms

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Supply voltage: 10+30 Vdc

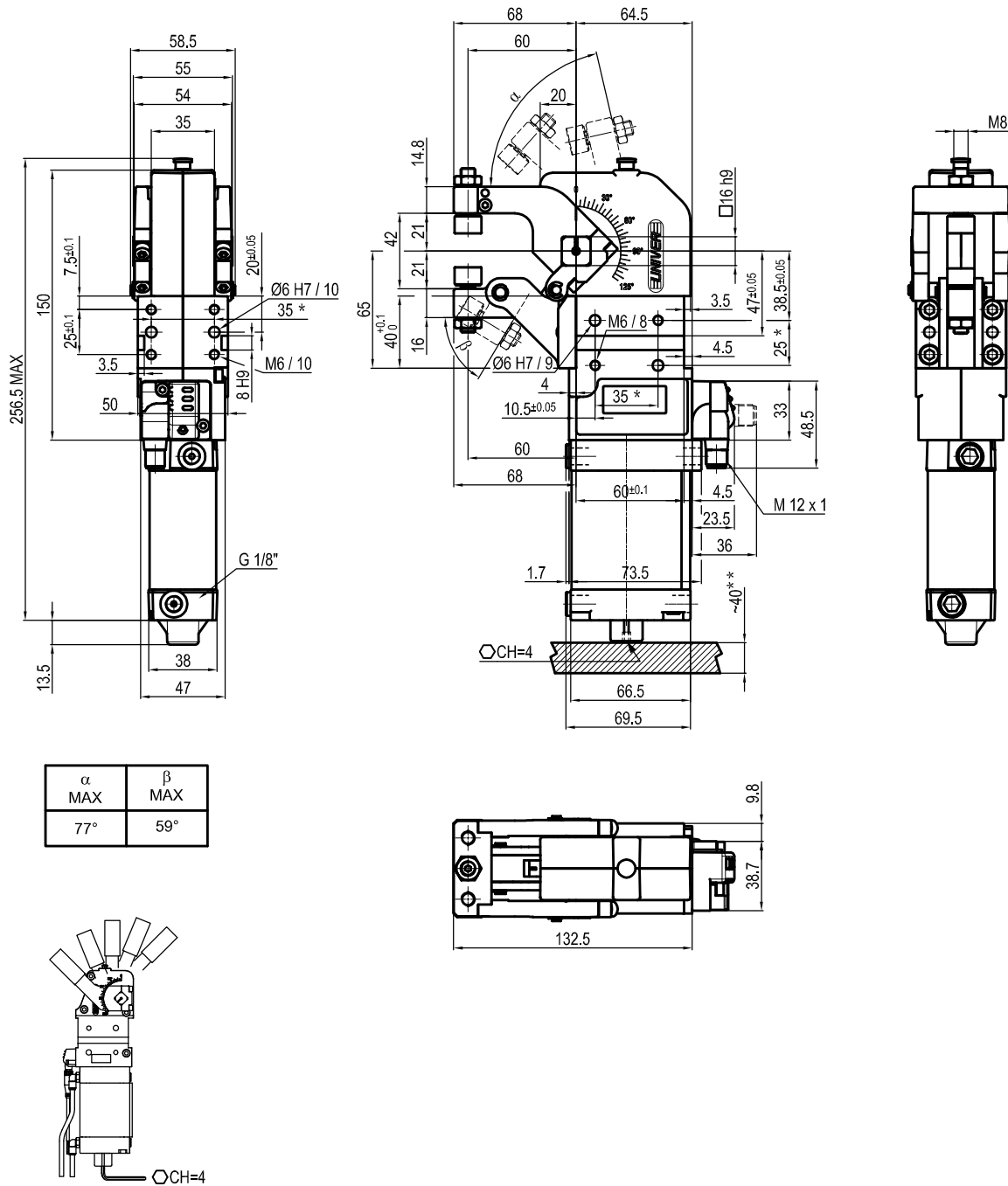
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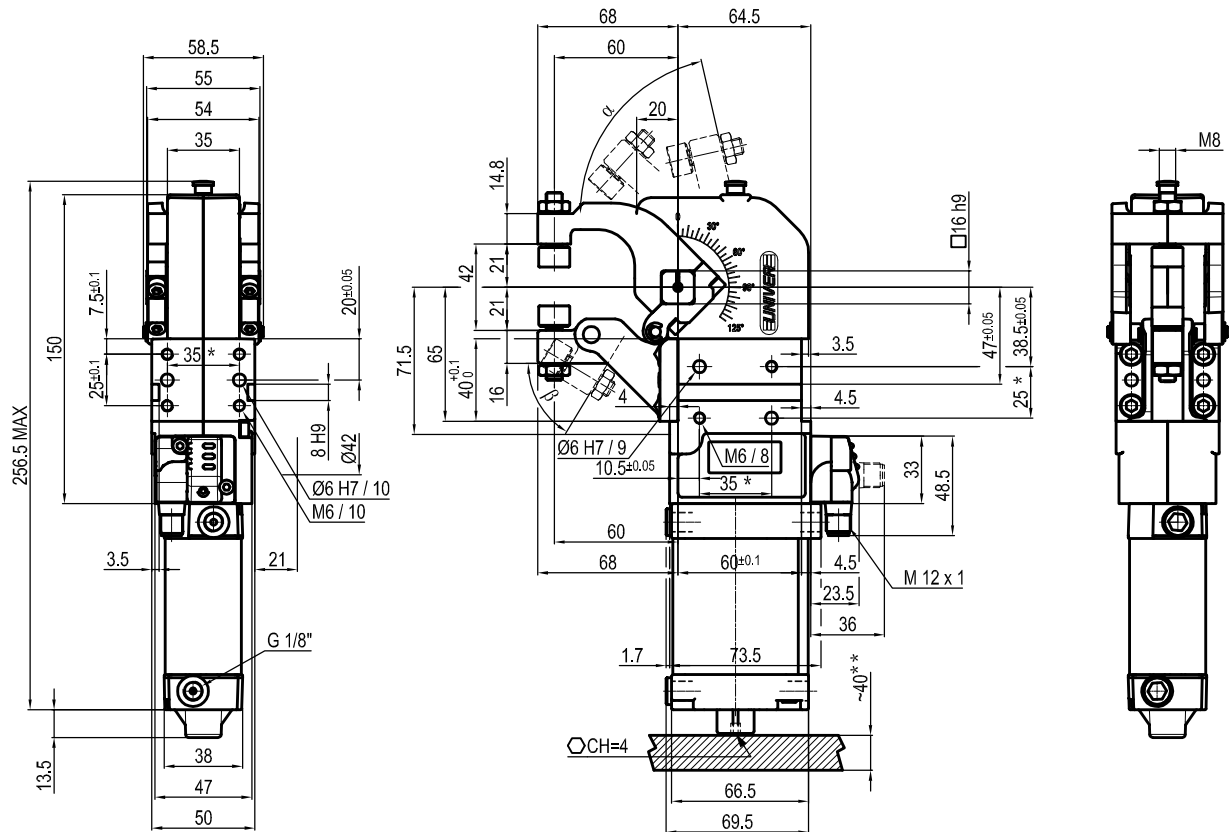


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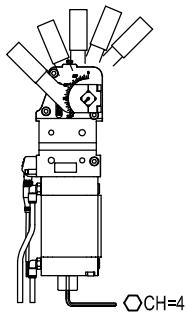
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$\alpha$ MAX	$\beta$ MAX
77°	59°

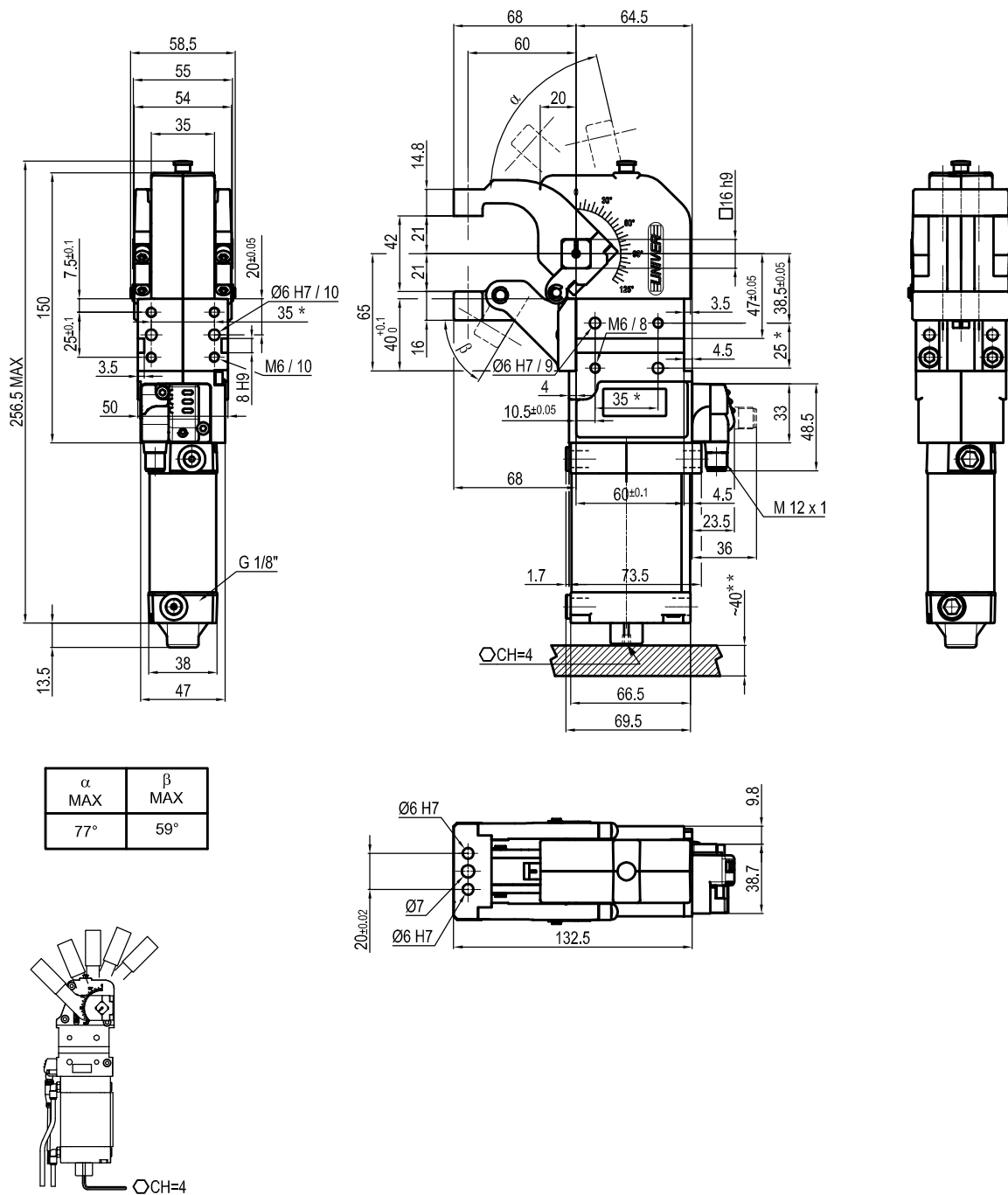


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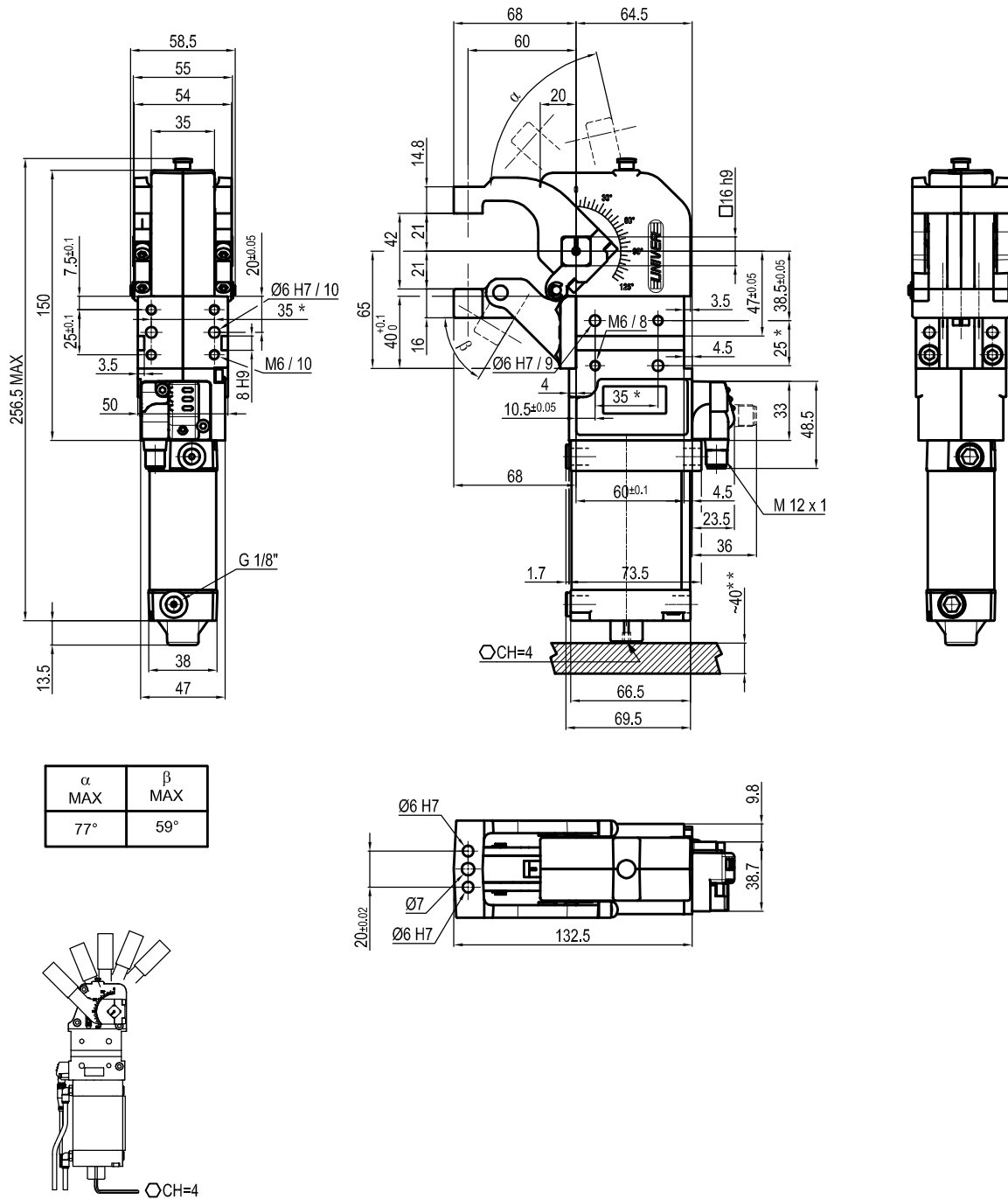


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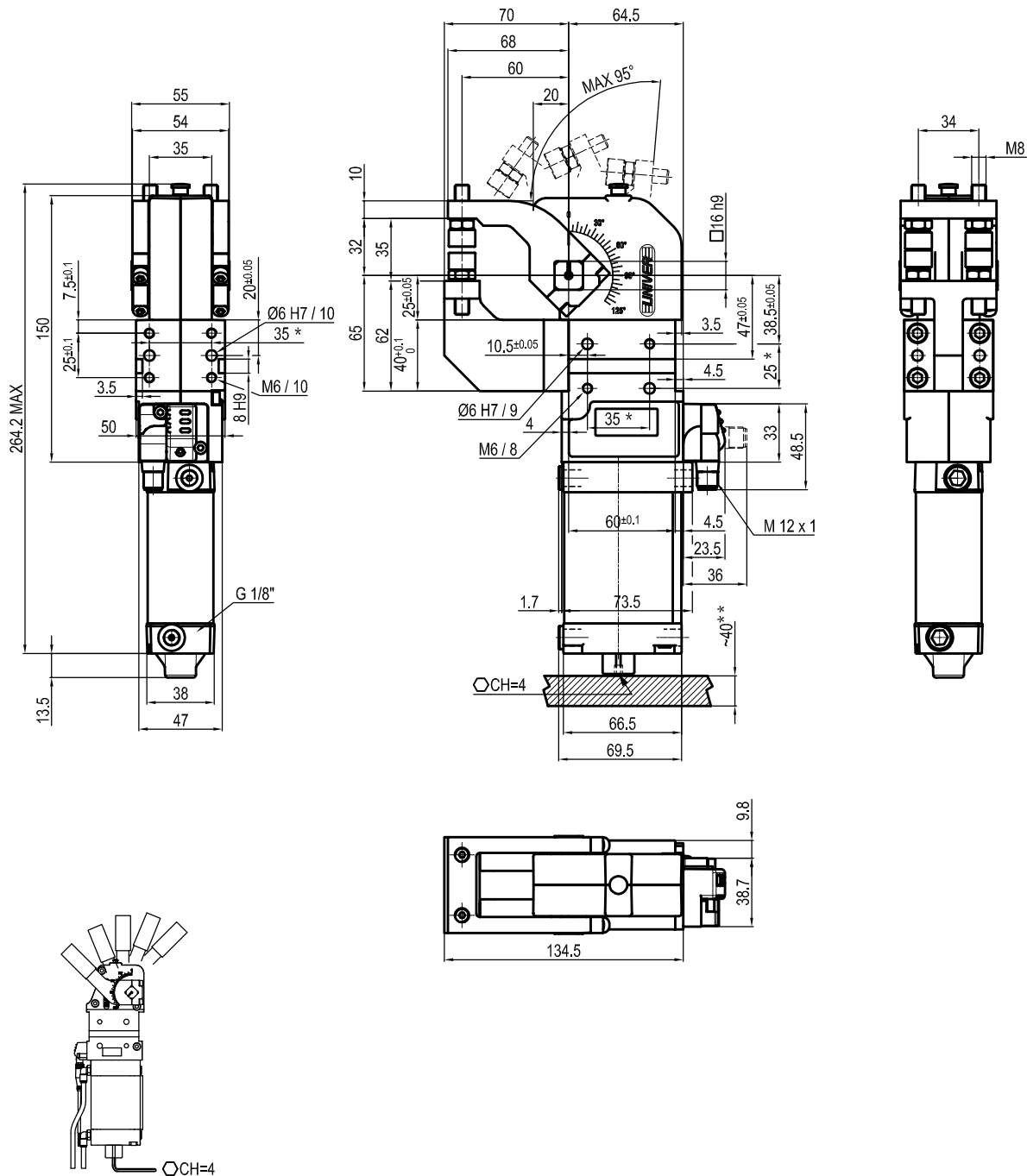
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Supply voltage: 10+30 Vdc

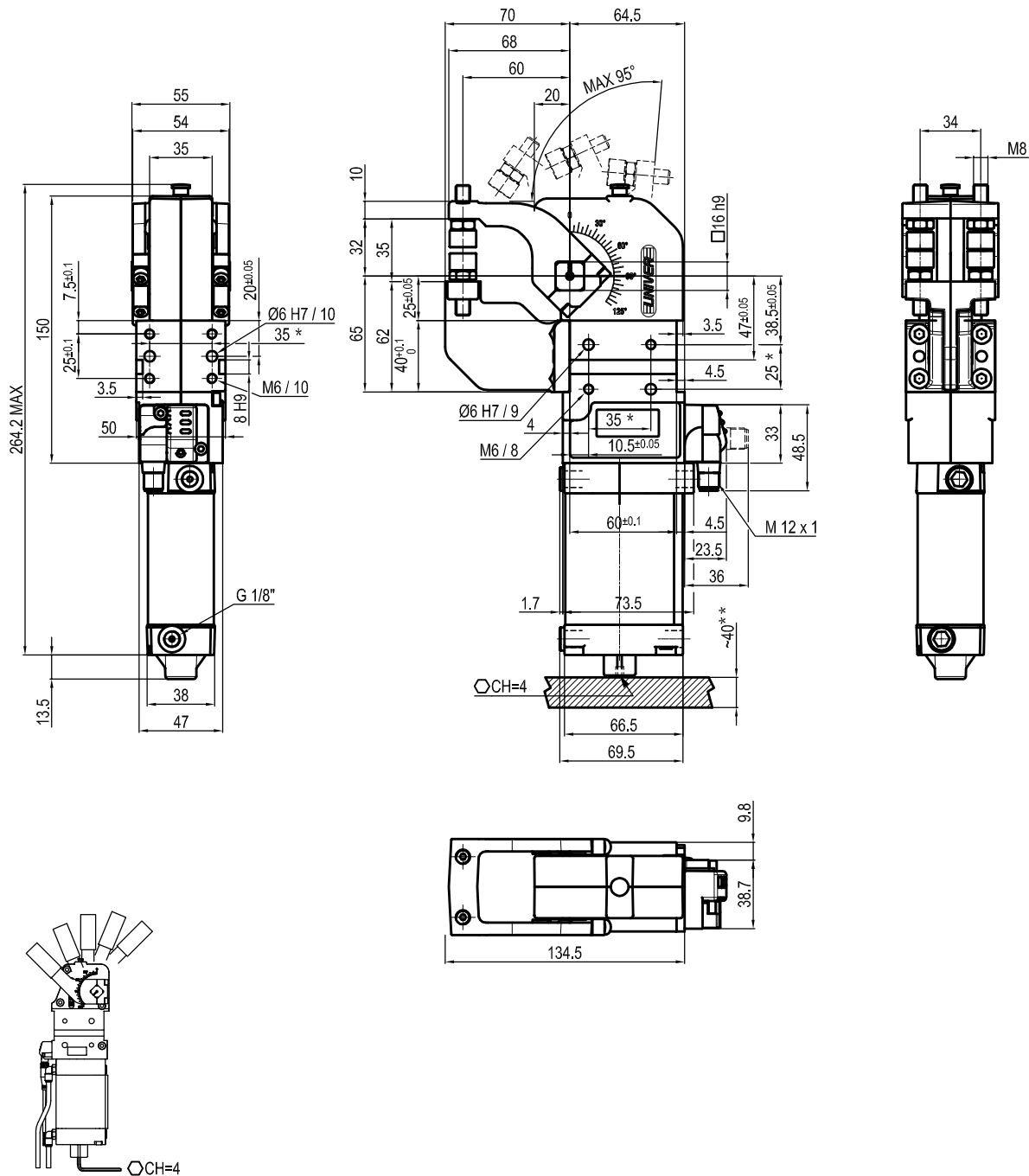
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